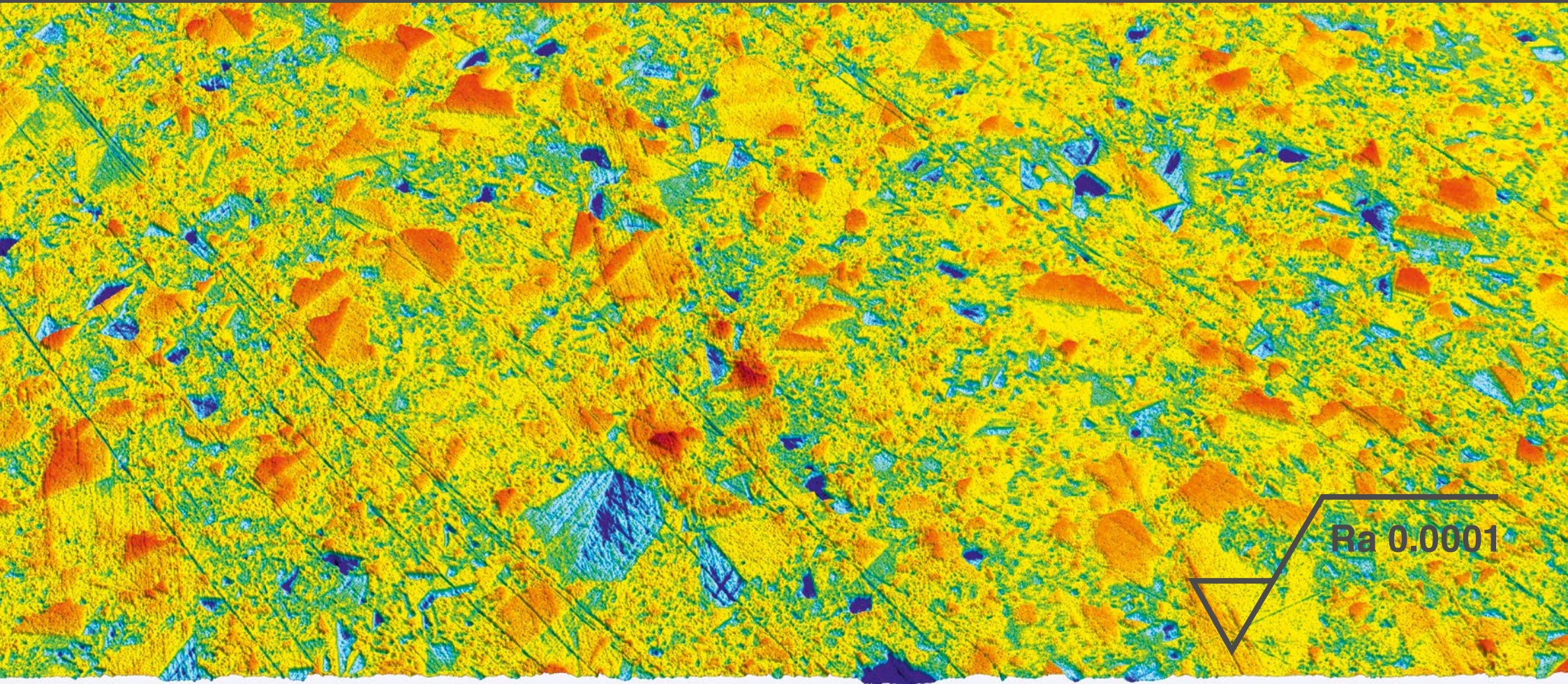






## optical 3D sensors based on coherence scanning (white-light) interferometry



| smartWLI sensor                           | nimbus8     | next                       | firebolt8     | compact          | nanoscan      | extended range |
|-------------------------------------------|-------------|----------------------------|---------------|------------------|---------------|----------------|
| camera                                    | 8.0 MP      | 1.3 MP / 2.3 MP / 5 MP     | 8.0 MP        | 2.3 MP / 5 MP    | 5 MP          | 2.3 MP         |
| speed                                     | 160 FPS     | 935 FPS / 169 FPS / 77 FPS | 160 FPS       | 169 FPS / 77 FPS | 77 FPS        | 169 FPS        |
| scanning range                            | 200 $\mu$ m | 200 $\mu$ m                | 400 $\mu$ m   | 400 $\mu$ m      | 400 $\mu$ m   | 5 mm           |
| topography reproducibility single scan    | < 0.05 nm   | < 0.05 nm                  | < 0.05 nm     | < 0.05 nm        | < 0.05 nm     | < 0.5 nm       |
| topography reproducibility 10 repetitions | < 0.02 nm   | < 0.02 nm                  | < 0.02 nm     | < 0.02 nm        | < 0.02 nm     | –              |
| objective turret                          | motorized   | motorized                  | –             | –                | –             | –              |
| objectives                                | 2.5x – 115x | 5x – 115x                  | 2.5x – 115x   | 2.5x – 115x      | 2.5x – 115x   | 2.5x – 115x    |
| long distance objectives                  | –           | –                          | 10x, 5x, 1.5x | 10x, 5x, 1.5x    | 10x, 5x, 1.5x | 10x, 5x, 1.5x  |

## ISO conform specified lateral period limit $D_{LIM}$ for the smartWLI series

|                          | magnification / LED        | 2.5x                                                                | 5x        | 10x         | 20x         | 50x         | 100x        | 115x         |
|--------------------------|----------------------------|---------------------------------------------------------------------|-----------|-------------|-------------|-------------|-------------|--------------|
| $D_{LIM} \mu m$          | 1.3 MP / 0.5x tube / green | 19.83                                                               | 10.24     | 4.96        | 2.74        | 1.36        | 0.84        | 0.73         |
|                          | 2.3 MP / 0.5x tube / green | 15.63                                                               | 8.14      | 3.94        | 2.23        | 1.15        | 0.75        | 0.64         |
|                          | 5 MP / 0.5x tube / green   | 12.63                                                               | 6.64      | 3.13        | 1.84        | 1           | 0.66        | 0.58         |
|                          | 5 MP / 1.0x tube / blue    | 7.98                                                                | 4.28      | 2.00        | 1.23        | 0.73        | 0.51        | 0.45         |
|                          | 8 MP / 1.x tube / green    | -                                                                   | 5.2       | 2.4         | 1.46        | 0.82        | 0.55        | 0.49         |
| spatial sampling $\mu m$ | 1.3 MP / 0.5x tube / green | 5.2                                                                 | 2.6       | 1.3         | 0.65        | 0.26        | 0.13        | 0.11         |
|                          | 2.3 MP / 0.5x tube / green | 3.8                                                                 | 1.9       | 0.96        | 0.48        | 0.19        | 0.1         | 0.08         |
|                          | 5 MP / 0.5x tube / green   | 2.8                                                                 | 1.4       | 0.69        | 0.35        | 0.14        | 0.07        | 0.06         |
|                          | 5 MP / 1.0x tube / blue    | 1.4                                                                 | 0.7       | 0.35        | 0.175       | 0.07        | 0.035       | 0.03         |
|                          | 8 MP / 1.x tube / green    | -                                                                   | 1.0       | 0.5         | 0.25        | 0.1         | 0.05        | 0.045        |
| FOV mm <sup>2</sup>      | 1.3 MP / 0.5x tube / green | 6.7 x 5.4                                                           | 3.4 x 2.7 | 1.6 x 1.4   | 0.83 x 0.68 | 0.34 x 0.27 | 0.16 x 0.14 | 0.15 x 0.12  |
|                          | 2.3 MP / 0.5x tube / green | 7.3 x 4.6                                                           | 3.7 x 2.3 | 1.8 x 1.2   | 0.91 x 0.58 | 0.37 x 0.23 | 0.18 x 0.12 | 0.16 x 0.1   |
|                          | 5 MP / 0.5x tube / green   | 6.8 x 5.7                                                           | 3.4 x 2.8 | 1.7 x 1.4   | 0.85 x 0.71 | 0.34 x 0.28 | 0.17 x 0.14 | 0.15 x 0.12  |
|                          | 5 MP / 1.0x tube / blue    | 3.4 x 2.8                                                           | 1.7 x 1.4 | 0.85 x 0.71 | 0.43 x 0.36 | 0.17 x 0.14 | 0.09 x 0.07 | 0.075 x 0.06 |
|                          | 8 MP / 1.x tube / green    |                                                                     | 3.4 x 2.2 | 1.7 x 1.1   | 0.85 x 0.55 | 0.34 x 0.22 | 0.17 x 0.11 | 0.15 x 0.1   |
| available systems        | 1.3 MP / 0.5x tube / green | smartWLI next                                                       |           |             |             |             |             |              |
|                          | 2.3 MP / 0.5x tube / green | smartWLI Scanner, smartWLI GBScope, smartWLI compact, smartWLI next |           |             |             |             |             |              |
|                          | 5 MP / 0.5x tube / green   | smartWLI compact, smartWLI next                                     |           |             |             |             |             |              |
|                          | 5 MP / 1.0x tube / blue    | smartWLI nanoscan                                                   |           |             |             |             |             |              |
|                          | 8 MP / 1.x tube / green    | smartWLI nimbus8, SmartWLI firebolt8                                |           |             |             |             |             |              |

## unique advantages of the smartWLI sensors based on superior calculation power

### optical 3D sensors with superior resolution

- HD-EPsi (high density extended phase shift interferometry) combines and extends interferometric measurement techniques for noise suppression

### increased acceptance angles on shine inclined surfaces

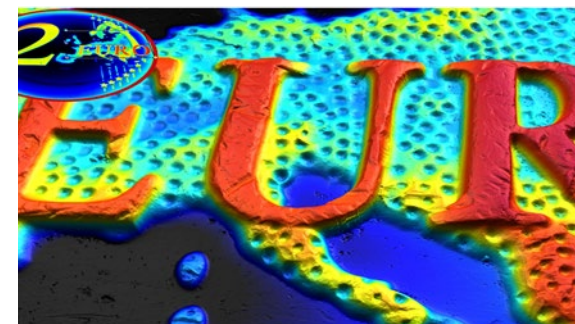
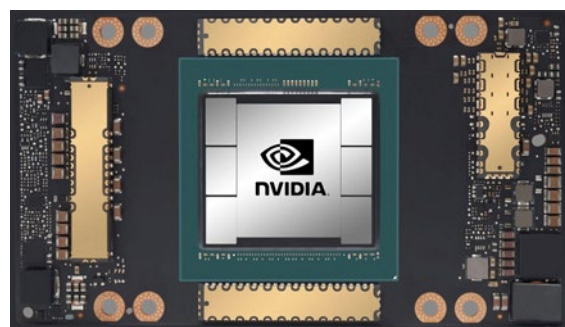
- image correction and contrast enhancement are used to eliminate the camera noise and amplify weak interference signals

### suppression of outliers on fine structures surfaces with a higher aspect ratio

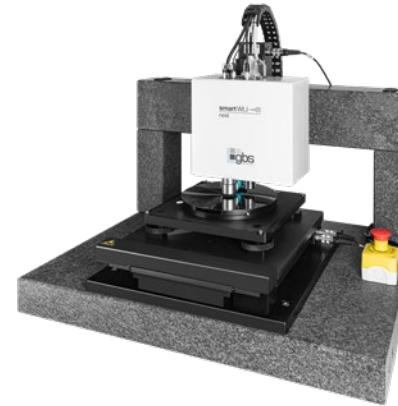
- AQC (advanced quality control) compares the camera signal FFT-based with ideal correlograms and eliminates outliers without filtering the 3D point cloud

### faster measurements and higher resolution save time and money

- CUDA programmed NVIDIA graphic boards are 100x faster than CPUs and enable the use of faster, higher-resolution cameras



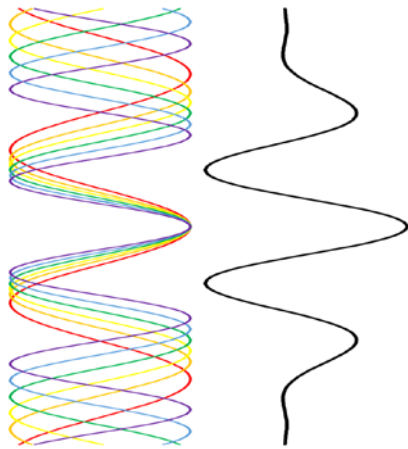
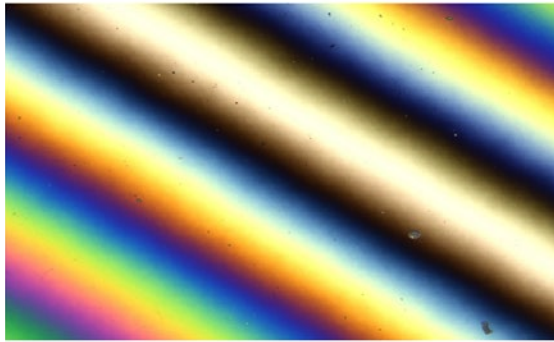
## optical 3D profilometer and system building kits



| smartWLI sensor                 | GBScanner                                                                                           | GBScope            | system building kits                                        | CylinderInspector3D |
|---------------------------------|-----------------------------------------------------------------------------------------------------|--------------------|-------------------------------------------------------------|---------------------|
| <b>sensors</b>                  | part of the system                                                                                  | part of the system | nimbus8, next, firebolt8, compact, nanoscan, extended range | part of the system  |
| <b>camera</b>                   | 2.3 MP / 169 FPS                                                                                    | 2.3 MP / 169 FPS   | see sensor specification                                    | 4 MP / 77 FPS       |
| <b>scanning range</b>           | 50 ... 200 mm                                                                                       | 50 ... 200 mm      | 200 $\mu$ m ... 200 mm                                      | 200 $\mu$ m         |
| <b>manual xy stages</b>         | –                                                                                                   | –                  | 100 x 100 mm <sup>2</sup>                                   | 360° rotation       |
| <b>motorized xy stages</b>      | 100 x 100 mm <sup>2</sup> ; 200 x 200 mm <sup>2</sup> , 300 x 300 mm <sup>2</sup> , granite portals |                    |                                                             | –                   |
| <b>tip-tilt</b>                 | manual                                                                                              | manual             | manual / motorized                                          | manual              |
| <b>objective turret</b>         | motorized                                                                                           | –                  | see sensor specification                                    | –                   |
| <b>objectives</b>               | 5x – 115x                                                                                           | 2.5x – 115x        | see sensor specification                                    | 5x – 115x           |
| <b>long distance objectives</b> | –                                                                                                   | 10x, 5x, 1.5x      | see sensor specification                                    | –                   |

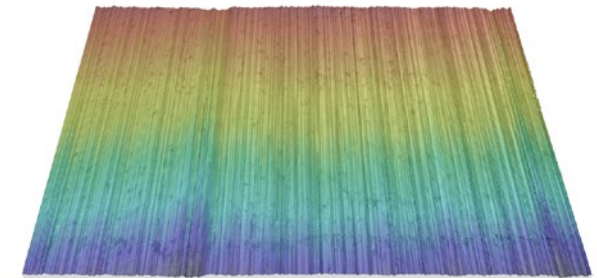
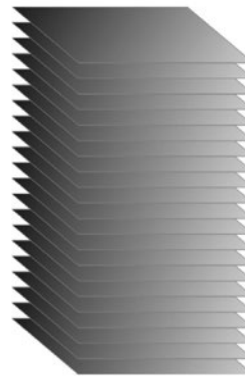
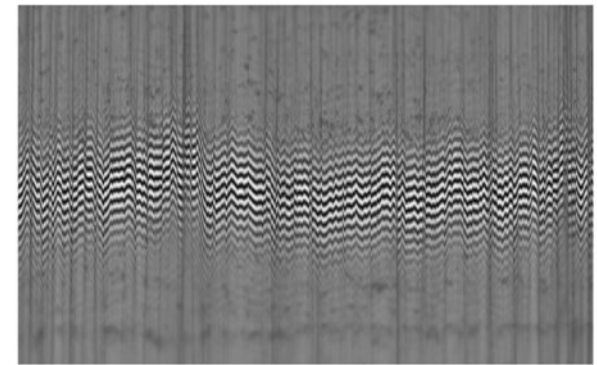
## coherence scanning (white-light) interferometry

interference on a mirror



The interference zone has its maximum in the focus plane. Light sources with optimized spectral properties are used to parametrize the interference zone size. The scanner moves the interference lens through the

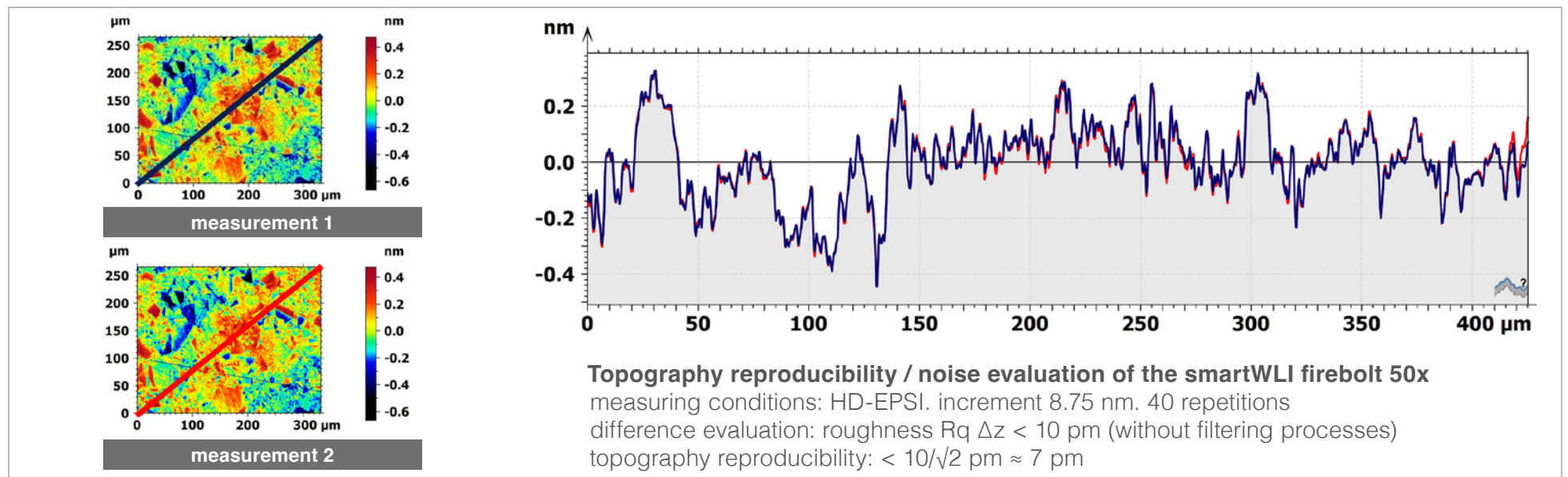
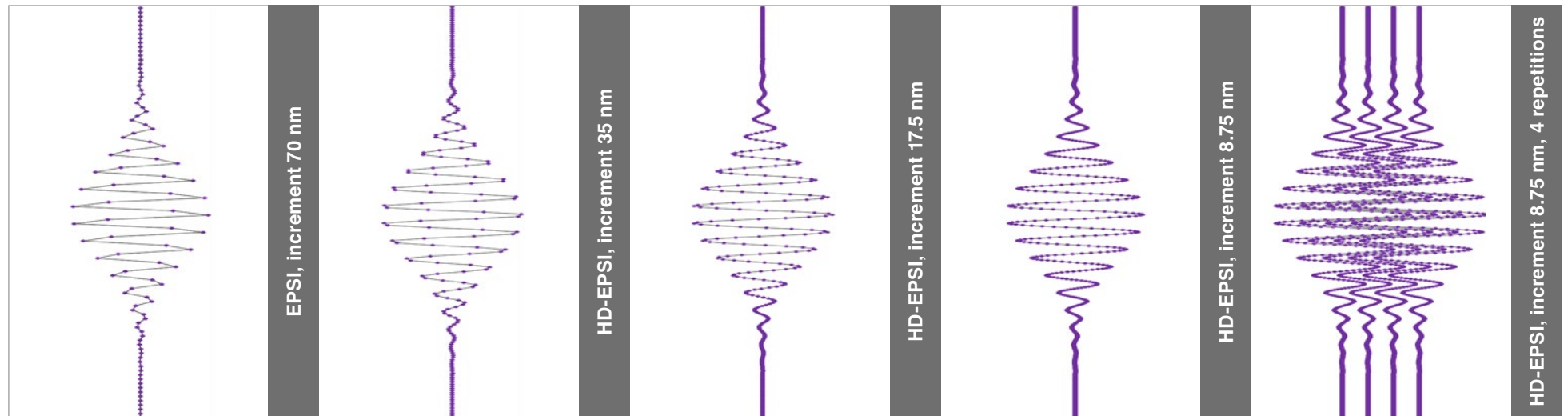
scanning process of a slightly inclined sample surface



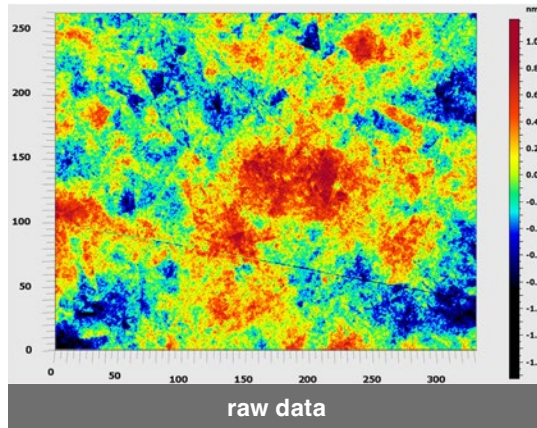
focal plane while the camera captures the interference signal. The software calculates the 3D geometry for each pixel.



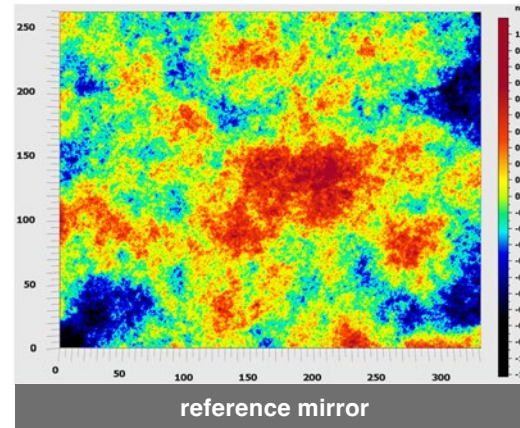
## superior height resolution based on HD-EPSI and profile averaging



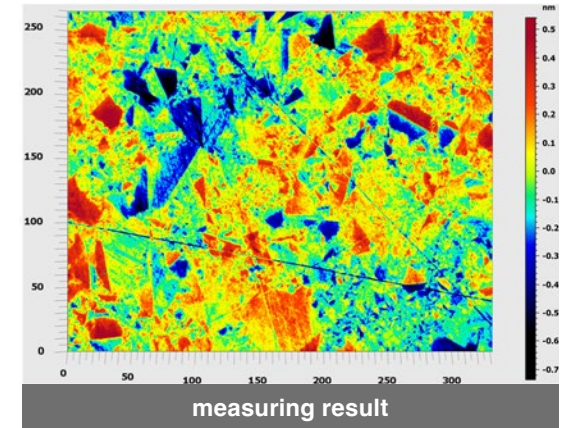
## excellent calibration for superior measurements



-



=



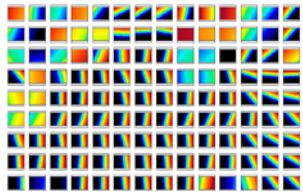
### excellent calibration for correct measurements

- calibration of piezo movements and capacity-controlled height scanning
- synchronization of scanner and camera
- lateral calibration using magnification specific dot targets
- determination of the effective wavelength from the light source with objective specific corrections
- determination of the coherence length and adapted range selection for HD-EPsi measurements

Sensor and system calibration form the basis for accurate measurements including error-free stitching processes. Internal tests and calibration certificates are included in the scope of delivery.

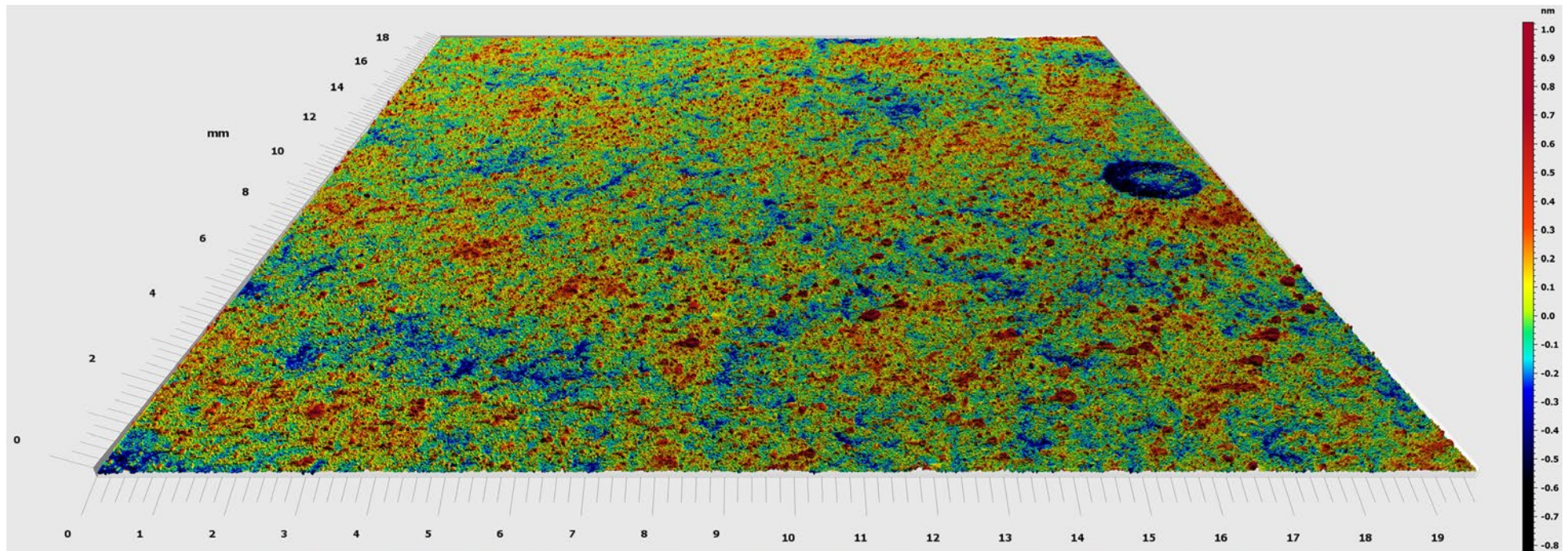


## smartSTITCH the basis for correct high resolution. large area measurements



### smartSTITCH for perfect measuring results using hundreds of single scans

XY table movements involve height and tilt errors. smartSTITCH algorithms utilize overlapping regions for height and angle compensation. This reduce stitching errors in roughness, flatness and form measurements below the visible range. The speed-optimized algorithms are integrated into the smartVIS3D scanning software.



raw data

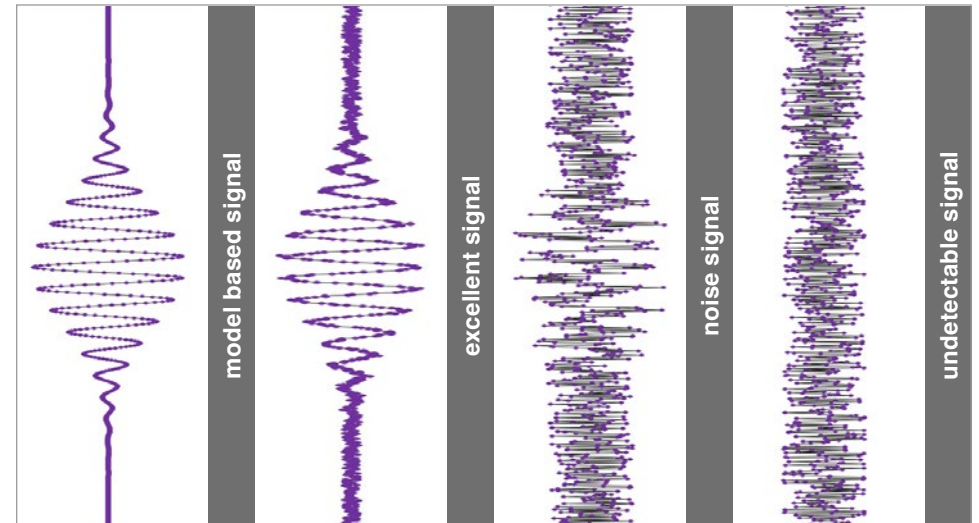
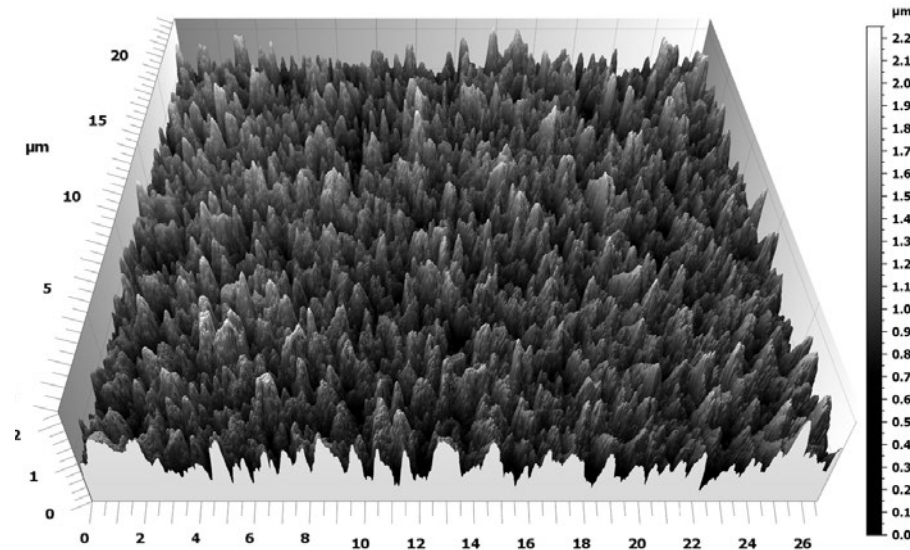
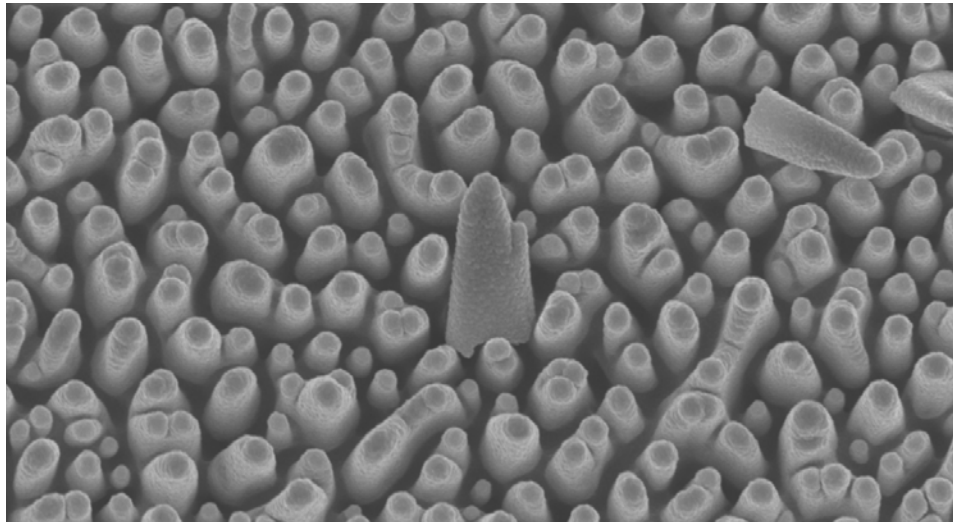


height compensation



height and angle compensation

## outlier free scanning – black silicon



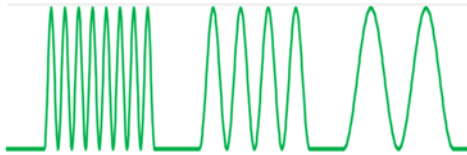
### AQC (advances quality control)

Computing power is used to continuously check the camera signal of each pixel in real time and quantify the agreement with an ideal interference signal. If vibrations, interference, and multiple reflections disrupt the signal to the point where the agreement falls below a certain threshold, the height is not calculated and the position remains invalid. This reduces the overall noise level, simplifies the measurement of smooth, inclined geometries, and enables the measurement of finely textured surfaces with high aspect ratios.

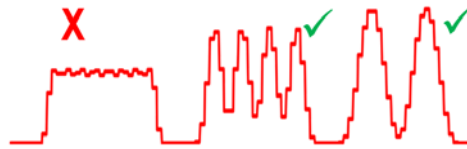


## excellent and objective tested lateral resolution / smartWLI nanoscan 115x objective

real sinus structures



measured structures



### the lateral period limit $D_{LIM}$ :

The lateral period limit is the wavelength once the amplitude of the measured profile drops below 50% of the real height (→ see ISO 25178 – 604).

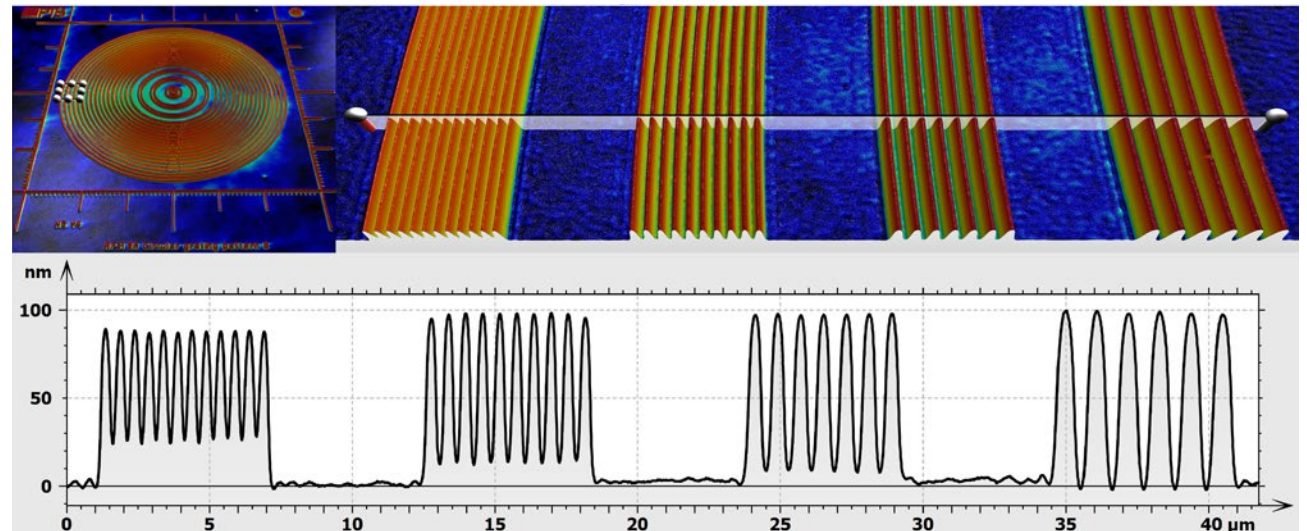
### intention of surface metrology:

The intention of surface metrology is in contrary to the microscopy not to resolve (see) structures but realize correct measurements. The lateral period  $D_{LIM}$  limit allows to specify, compare and select optical 3D profiler's objective and correctly.

### selection criteria:

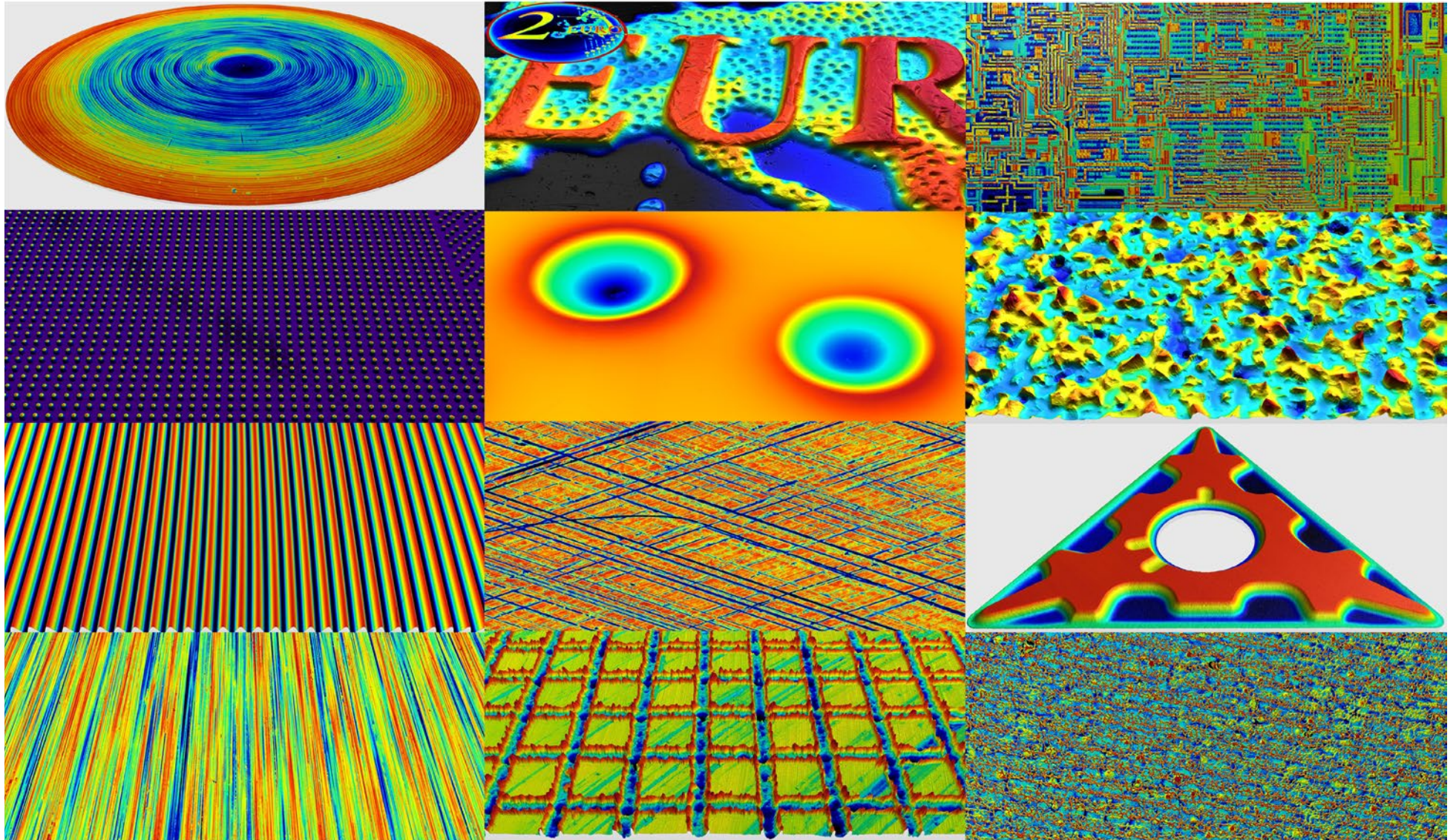
roughness measurements:  $D_{LIM} < Ral$  (autocorrelation length → see TracOptic praxis guide optical roughness measurement)

feature seize:  $D_{LIM} < \frac{1}{2} xy \text{ dimensions}$  ( $D_{LIM}$  is only a 50% criterion and must be smaller)



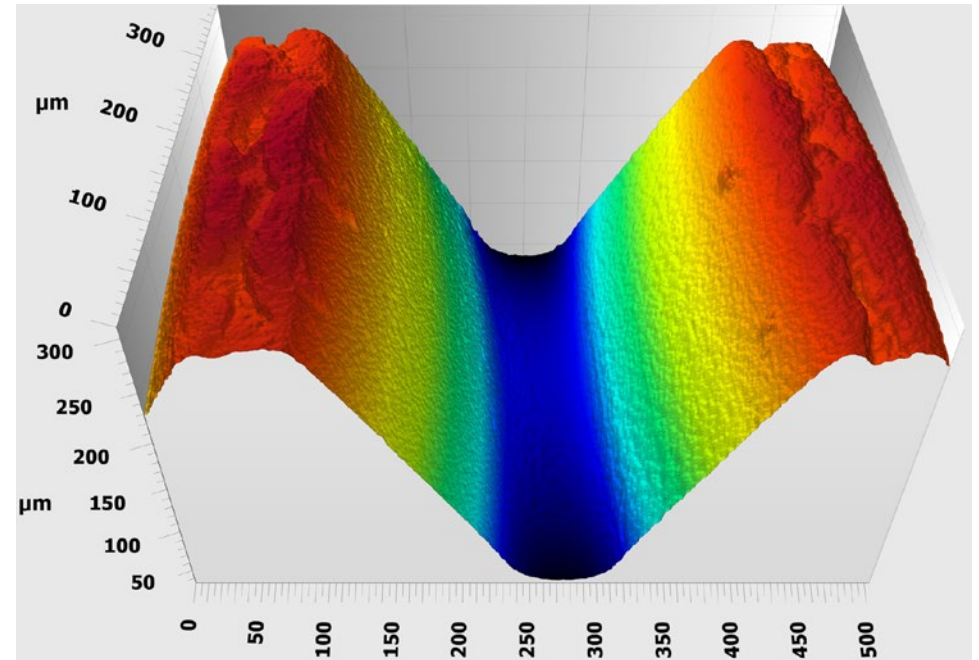
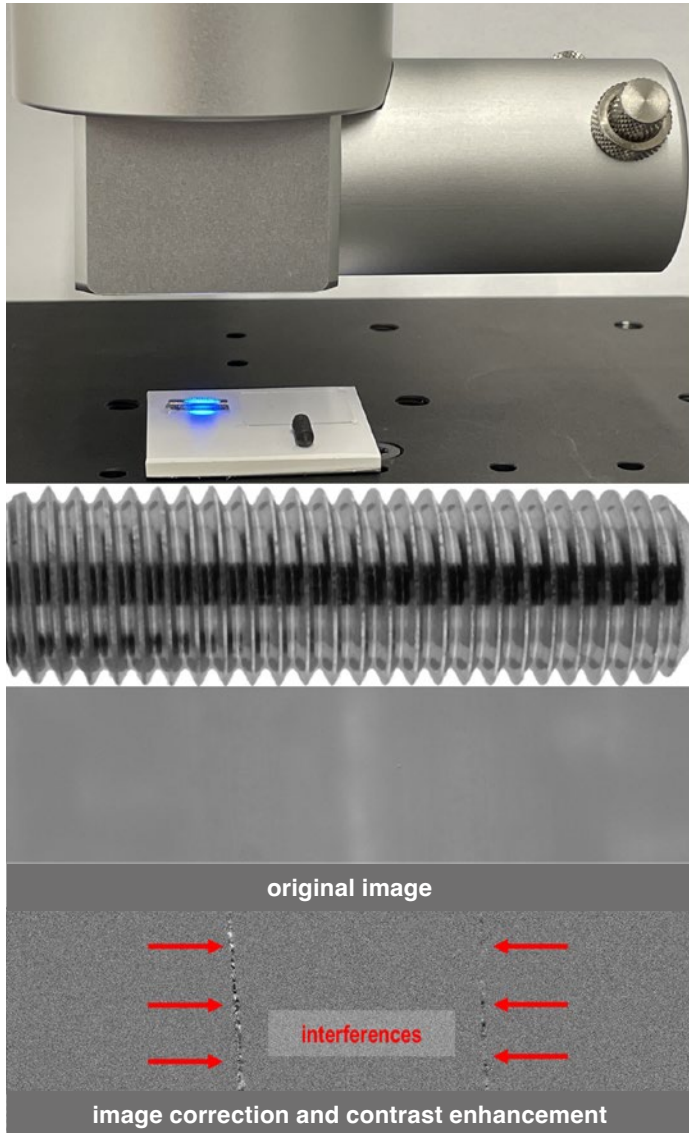


## application examples for smartWLI profilers





## increased acceptance angles



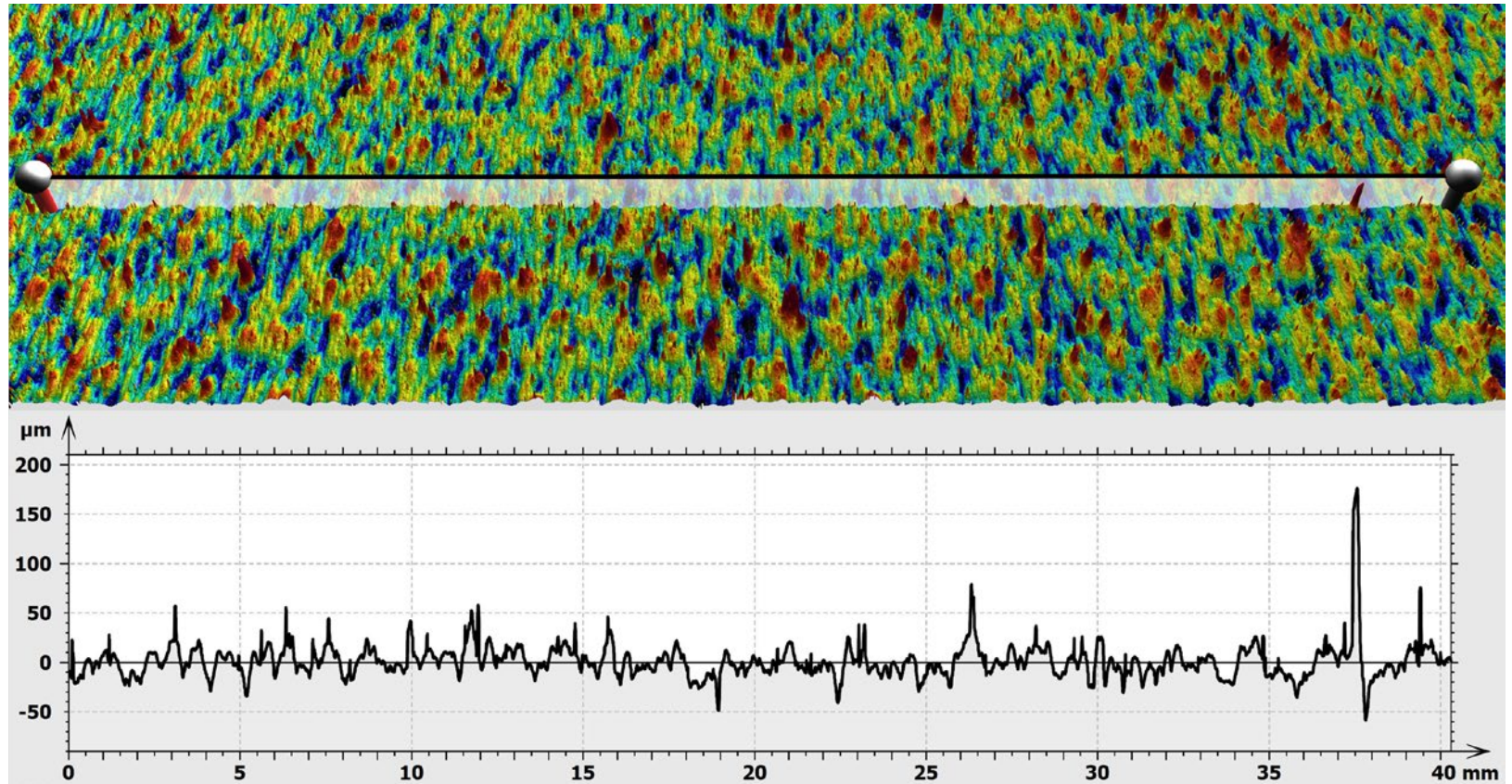
### tests on a shine stainless steel M2 screw using a 10x LD objective:

Screws are inexpensive, freely available, and have a standardized geometry with a flank angle of  $60^\circ$ . Due to the lack of standards and standardized tests, such objects allow for a good comparison of optical 3D profilers.

### image correction and contrast enhancement:

Not visible in the grabbed camera images - the contrast enhancement shows the interference zone and enables the interferometric calculation of the 3D data.

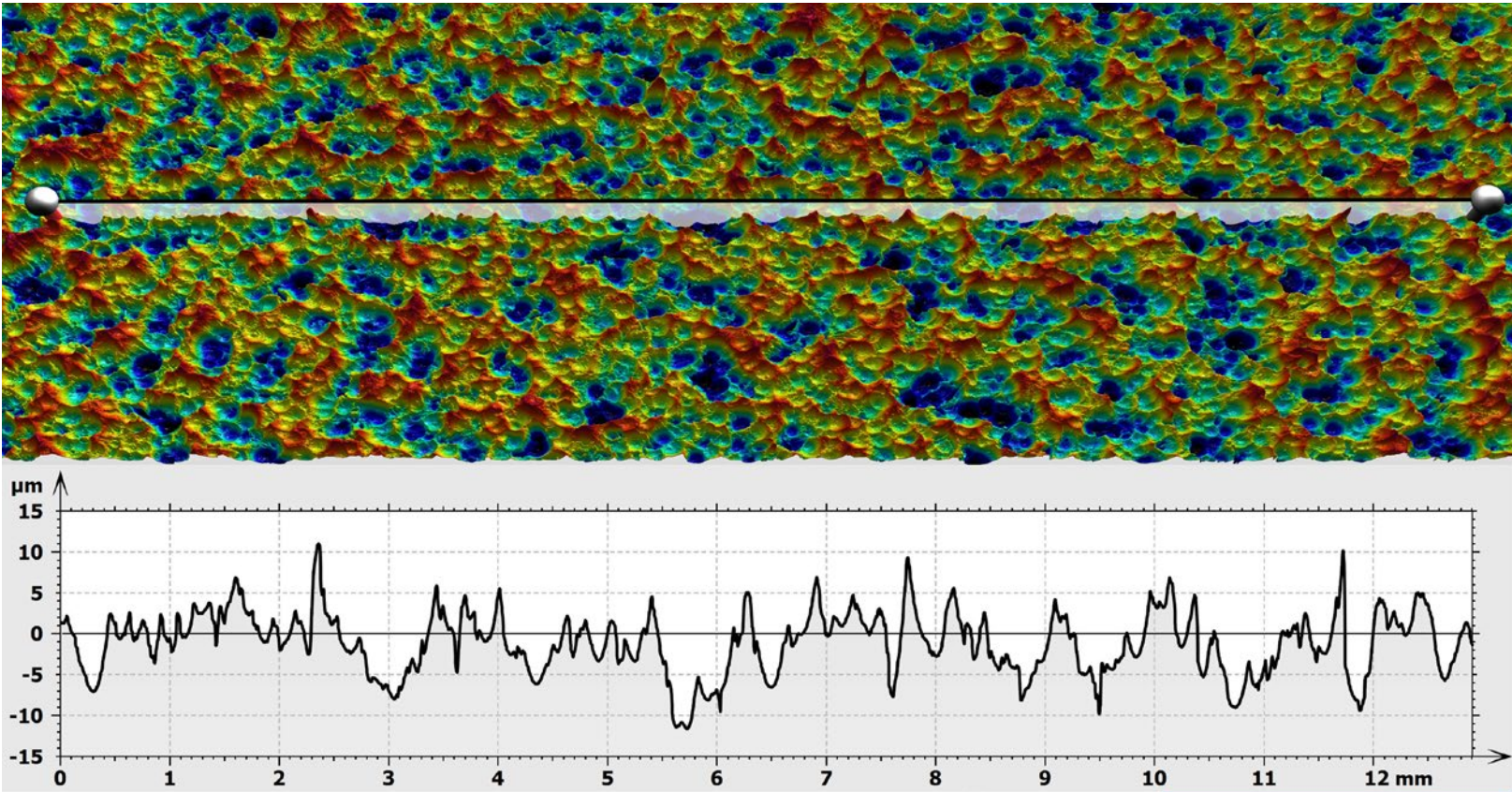
## metal printed surface

ISO 21920 setting class Sc5 (upper tolerance limit U:  $R_a > 10 \mu\text{m}$ )

|                                             |                  |                         |                   |                           |                    |
|---------------------------------------------|------------------|-------------------------|-------------------|---------------------------|--------------------|
| nesting index $N_{ic}$ / cutoff $\lambda_c$ | 8 mm             | sampling distance $d_x$ | $< 5 \mu\text{m}$ | measured height parameter |                    |
| evaluation length $l_e$                     | 40 mm            | section length $l_{sc}$ | 8 mm              | Rz                        | 118 $\mu\text{m}$  |
| nesting index $N_{is}$ / cutoff $\lambda_s$ | 25 $\mu\text{m}$ | number of sections      | 5                 | Ra                        | 11.0 $\mu\text{m}$ |

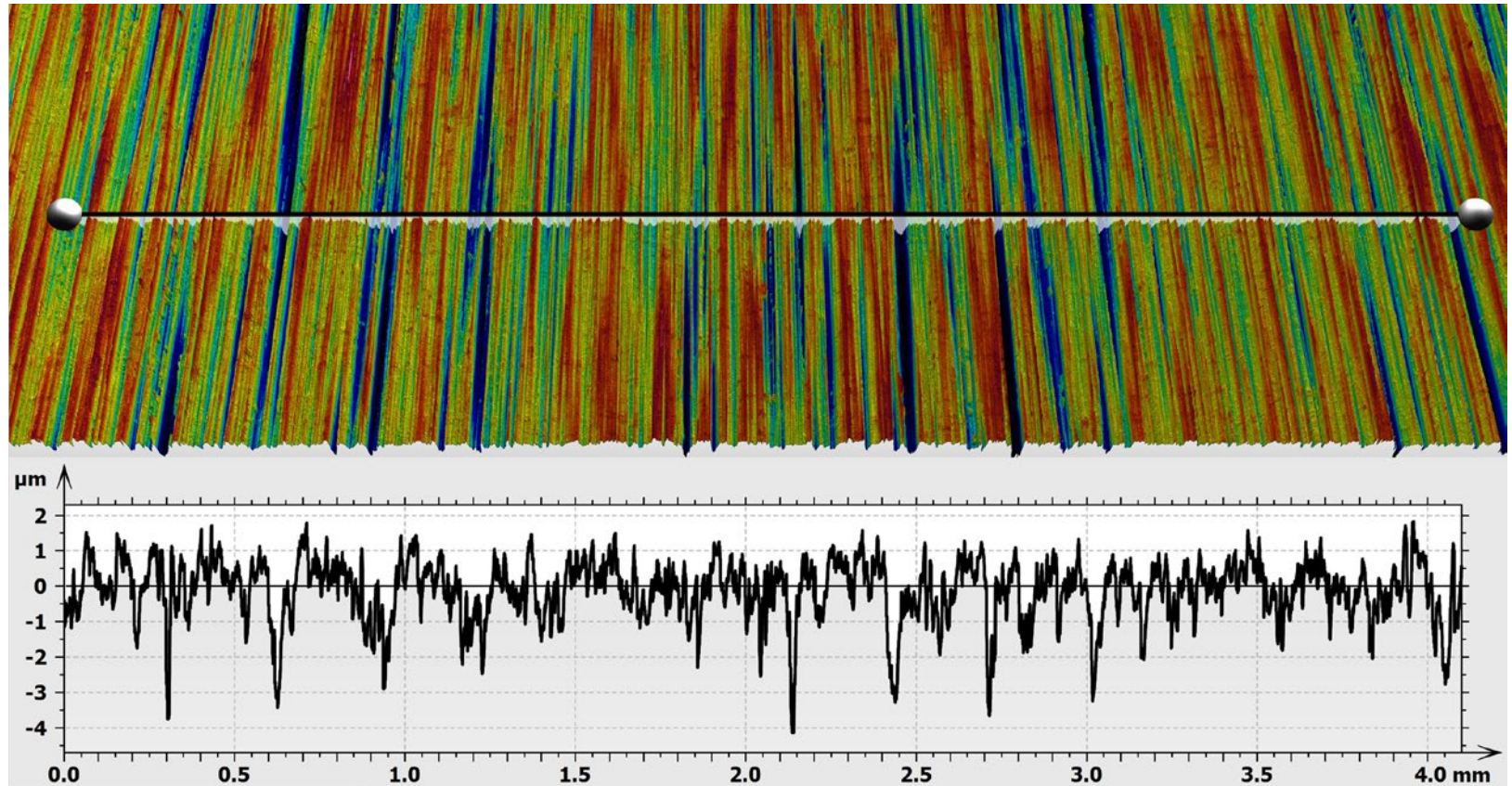


# blasted aluminum surface



| ISO 21920 setting class Sc4 (upper tolerance limit U: $2 < Ra \leq 10 \mu m$ ) |           |                         |               |                           |              |
|--------------------------------------------------------------------------------|-----------|-------------------------|---------------|---------------------------|--------------|
| nesting index $N_{ic}$ / cutoff $\lambda_c$                                    | 2.5 mm    | sampling distance $d_x$ | $< 1.5 \mu m$ | measured height parameter |              |
| evaluation length $l_e$                                                        | 12.5 mm   | section length $l_{sc}$ | 2.5 mm        | Rz                        | 16.4 $\mu m$ |
| nesting index $N_{is}$ / cutoff $\lambda_s$                                    | 8 $\mu m$ | number of sections      | 5             | Ra                        | 2.61 $\mu m$ |

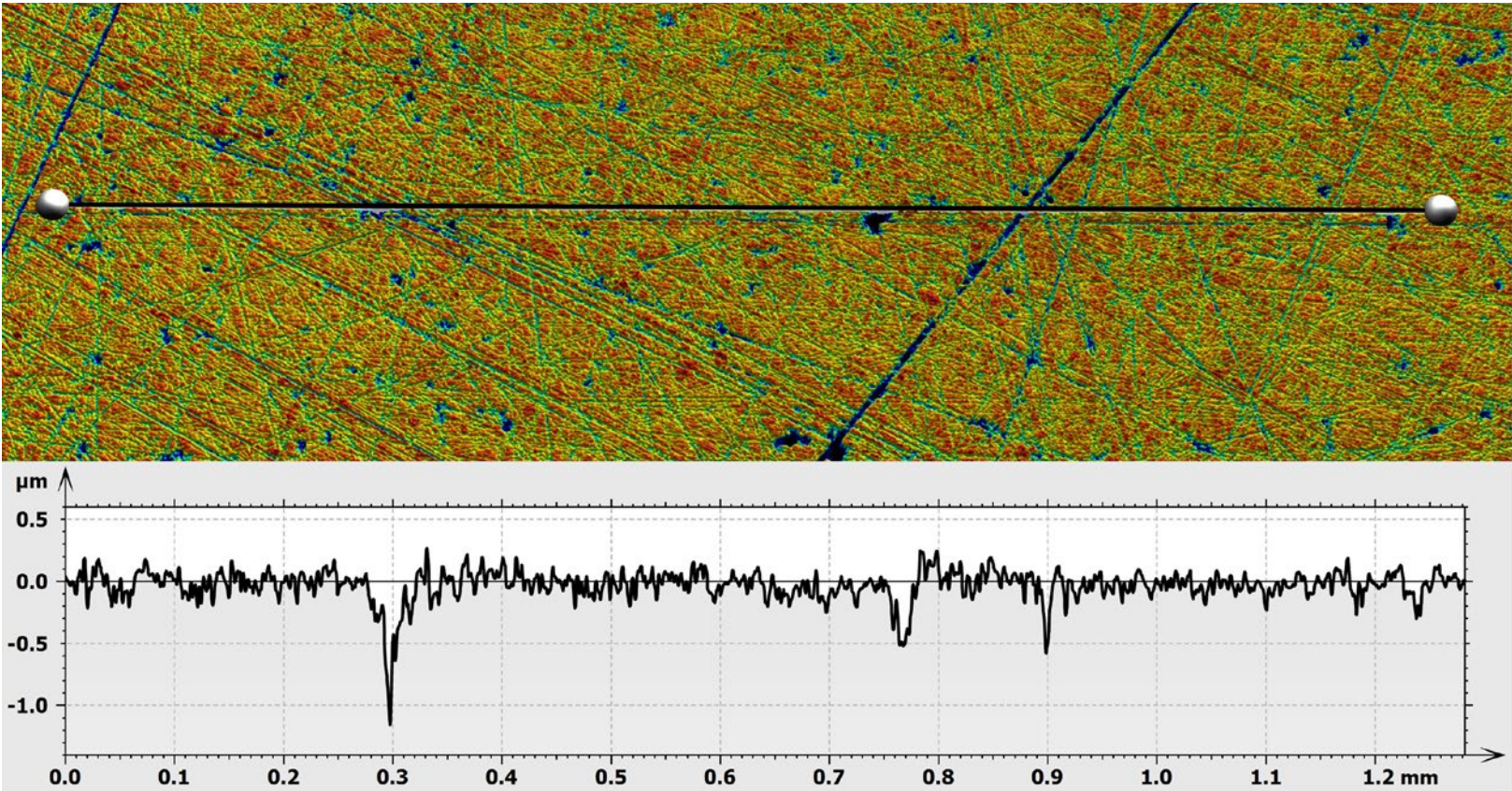
## grind surface

ISO 21920 setting class Sc3 (upper tolerance limit U:  $0.1 < Ra \leq 2 \mu m$ )

|                                             |             |                         |               |                           |               |
|---------------------------------------------|-------------|-------------------------|---------------|---------------------------|---------------|
| nesting index $N_{ic}$ / cutoff $\lambda_c$ | 0.8 mm      | sampling distance $d_x$ | $< 0.5 \mu m$ | measured height parameter |               |
| evaluation length $l_e$                     | 4 mm        | section length $l_{sc}$ | 0.8 mm        | Rz                        | $4.48 \mu m$  |
| nesting index $N_{is}$ / cutoff $\lambda_s$ | $2.5 \mu m$ | number of sections      | 5             | Ra                        | $0.637 \mu m$ |



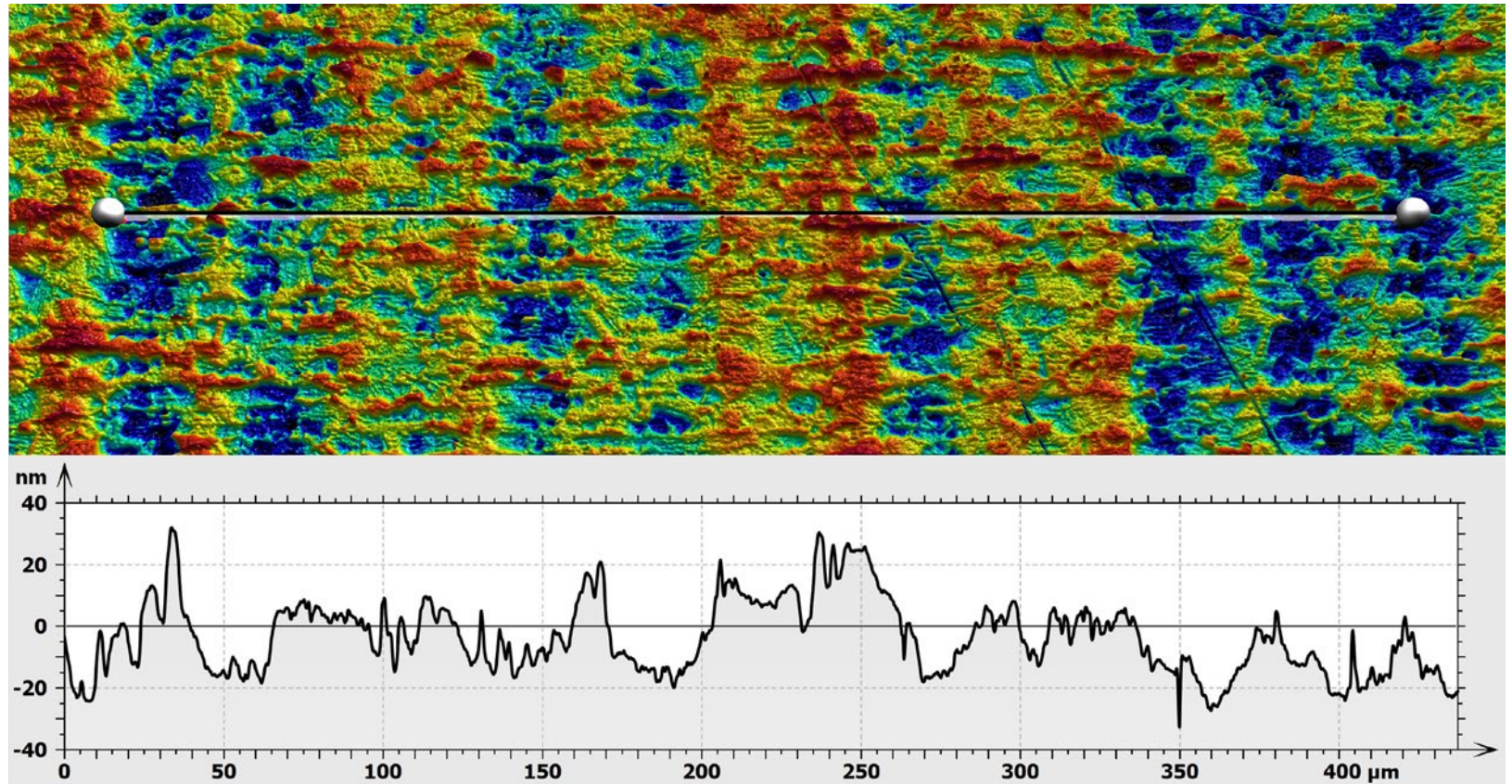
polished steel



| ISO 21920 setting class Sc2 (upper tolerance limit U: $0.02 < Ra \leq 0.1 \mu m$ ) |              |                         |               |                           |                |
|------------------------------------------------------------------------------------|--------------|-------------------------|---------------|---------------------------|----------------|
| nesting index $N_{ic}$ / cutoff $\lambda_c$                                        | 0.25 mm      | sampling distance $d_x$ | $< 0.5 \mu m$ | measured height parameter |                |
| evaluation length $l_e$                                                            | 1.25 mm      | section length $l_{sc}$ | 0.25 mm       | Rz                        | 0.669 $\mu m$  |
| nesting index $N_{is}$ / cutoff $\lambda_s$                                        | 0.25 $\mu m$ | number of sections      | 5             | Ra                        | 0.0767 $\mu m$ |



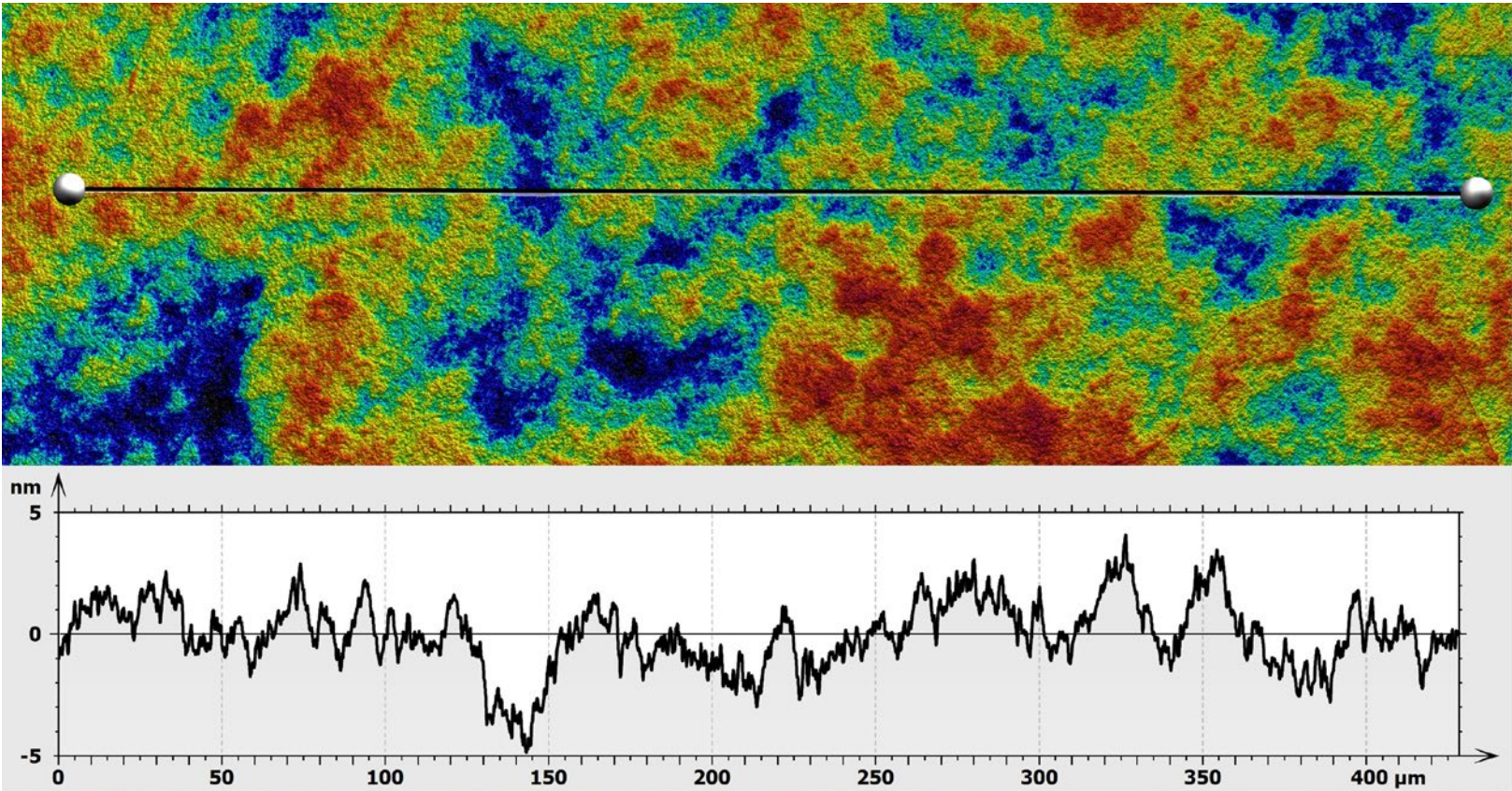
## chromed surface

ISO 21920 setting class Sc1 (upper tolerance limit U:  $R_a < 0.1 \mu\text{m}$ )

|                                             |                    |                         |                     |                           |         |
|---------------------------------------------|--------------------|-------------------------|---------------------|---------------------------|---------|
| nesting index $N_{ic}$ / cutoff $\lambda_c$ | 0.08 mm            | sampling distance $d_x$ | $< 0.5 \mu\text{m}$ | measured height parameter |         |
| evaluation length $l_e$                     | 0.4 mm             | section length $l_{sc}$ | 0.08 mm             | Rz                        | 32.2 nm |
| nesting index $N_{is}$ / cutoff $\lambda_s$ | 0.08 $\mu\text{m}$ | number of sections      | 5                   | Ra                        | 6.45 nm |

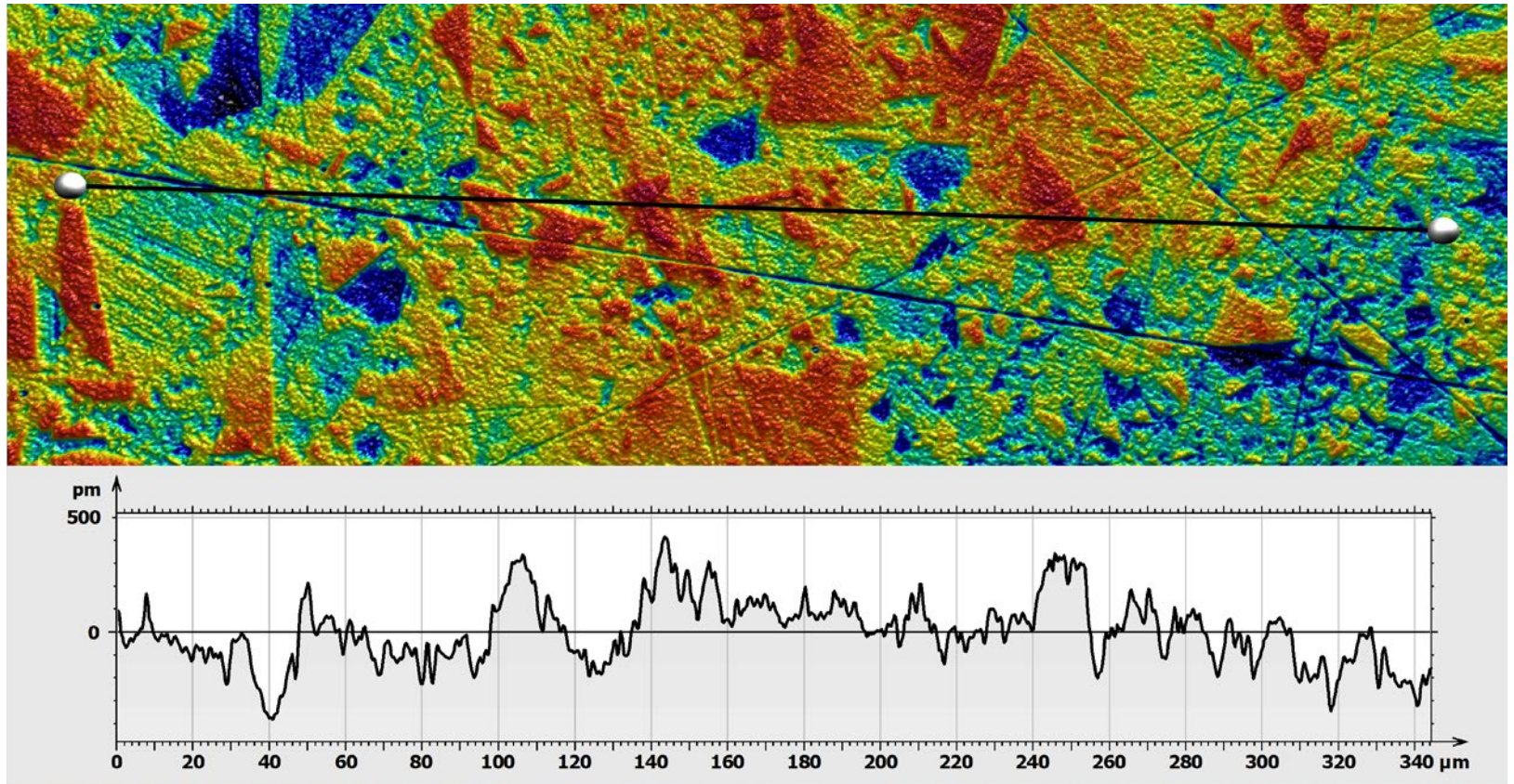


polished wafer



| ISO 21920 setting class Sc1 (upper tolerance limit U: Ra < 0.1 μm) |         |                                  |          |                           |          |
|--------------------------------------------------------------------|---------|----------------------------------|----------|---------------------------|----------|
| nesting index N <sub>ic</sub> / cutoff λ <sub>c</sub>              | 0.08 mm | sampling distance d <sub>x</sub> | < 0.5 μm | measured height parameter |          |
| evaluation length l <sub>e</sub>                                   | 0.4 mm  | section length l <sub>sc</sub>   | 0.08 mm  | Rz                        | 4.02 nm  |
| nesting index N <sub>is</sub> / cutoff λ <sub>s</sub>              | 0.08 μm | number of sections               | 5        | Ra                        | 0.770 nm |

## super polished SiC mirror



ISO 21920 setting class Sc1 (upper tolerance limit U:  $R_a < 0.1 \mu\text{m}$ )

|                                             |                    |                         |                     |                           |         |
|---------------------------------------------|--------------------|-------------------------|---------------------|---------------------------|---------|
| nesting index $N_{ic}$ / cutoff $\lambda_c$ | 0.08 mm            | sampling distance $d_x$ | $< 0.5 \mu\text{m}$ | measured height parameter |         |
| evaluation length $l_e$                     | 0.4 mm             | section length $l_{sc}$ | 0.08 mm             | Rz                        | 456 pm  |
| nesting index $N_{is}$ / cutoff $\lambda_s$ | 0.08 $\mu\text{m}$ | number of sections      | 5                   | Ra                        | 80.2 pm |



## UCS-1 (universal confirmation standard)

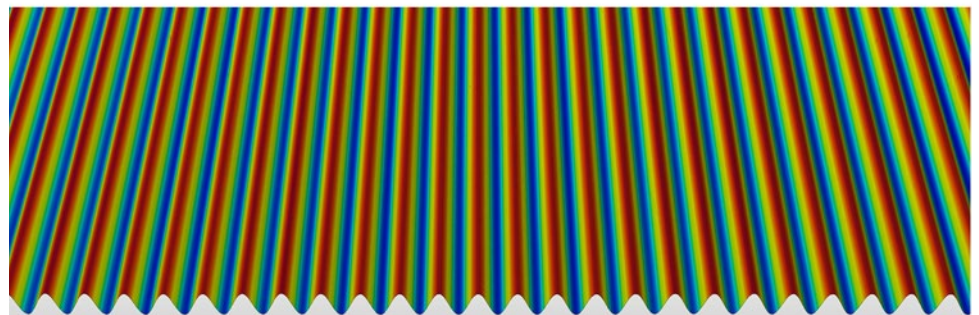
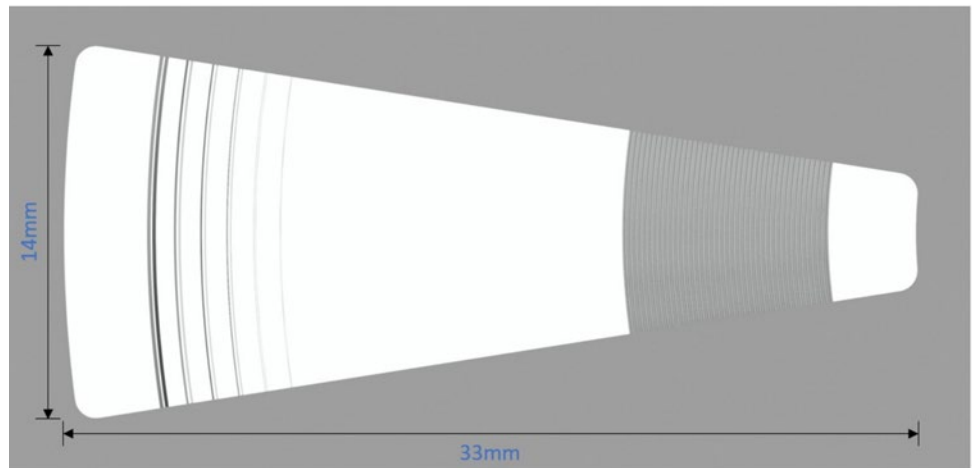
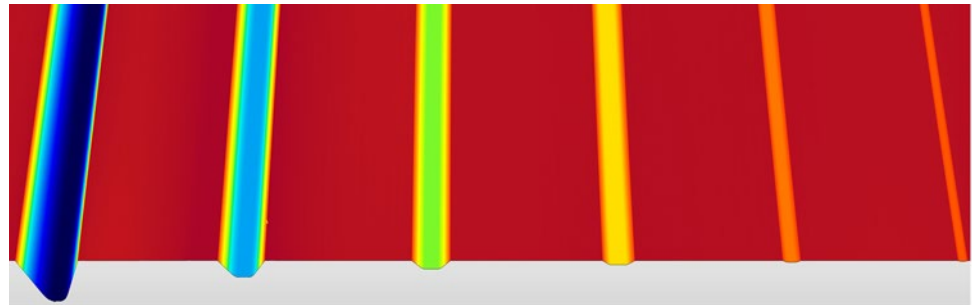
| groove depth d |                                |                              |
|----------------|--------------------------------|------------------------------|
| groove number  | nominal depth in $\mu\text{m}$ | uncertainty in $\mu\text{m}$ |
| 1              | 50                             | 0.05                         |
| 2              | 20                             | 0.04                         |
| 3              | 10                             | 0.03                         |
| 4              | 5                              | 0.03                         |
| 5              | 2                              | 0.03                         |
| 6              | 1                              | 0.03                         |

| sinus structure – Ra           |                              |
|--------------------------------|------------------------------|
| nominal value in $\mu\text{m}$ | uncertainty in $\mu\text{m}$ |
| 0.16                           | 0.01                         |

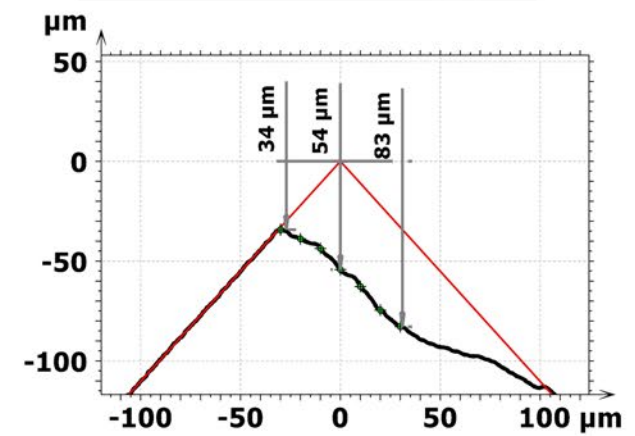
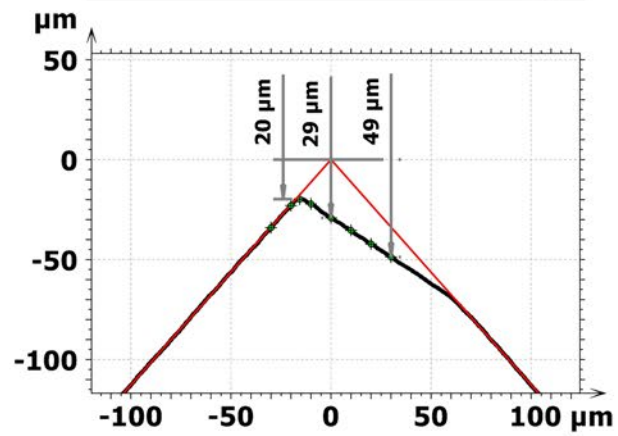
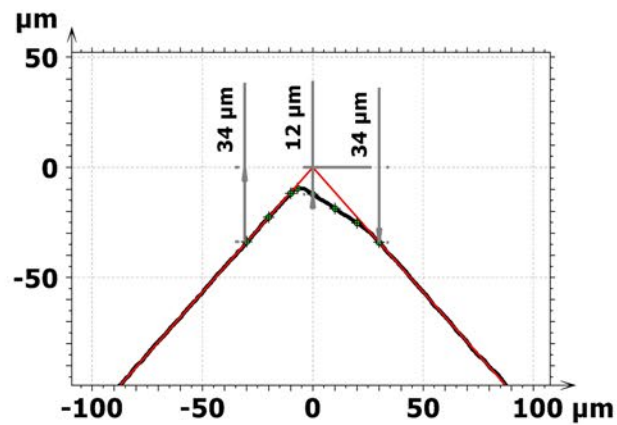
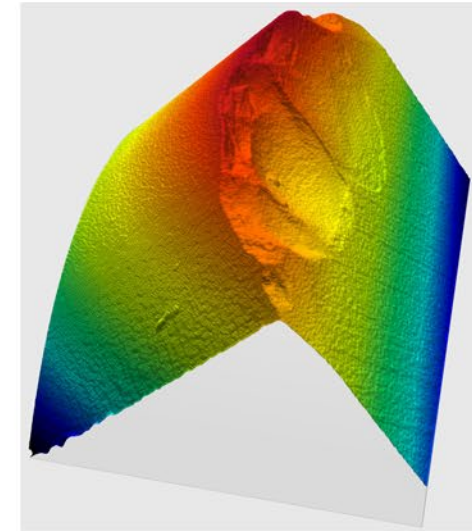
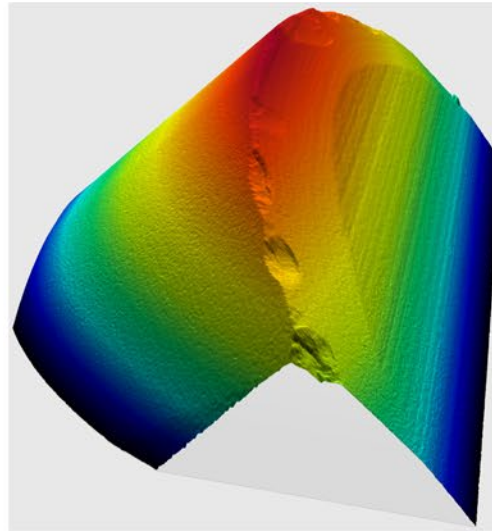
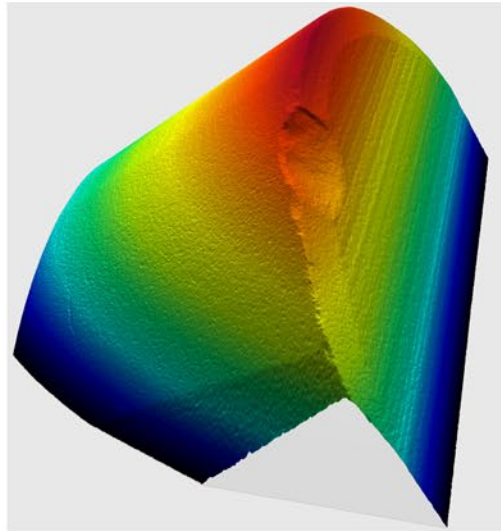


### advantages of the universal confirmation standard UCS-1:

The UCS-1 is available with traceable factory calibration and is suitable not only for optical 3D profilers but also for tactile instruments. Maximum flank angles of  $20^\circ$  enable measurements and calibrations with tactile profilometers. A hardened stainless-steel block offers high corrosion and scratch resistance. Thanks to its long service life and easy cleaning, it is ideal for daily use in industrial environments. Seven steps, a sinusoidal zone for roughness measurements, and a smooth zone for topography reproducibility tests allow for flexible use of the surface standard.



## cutting edges



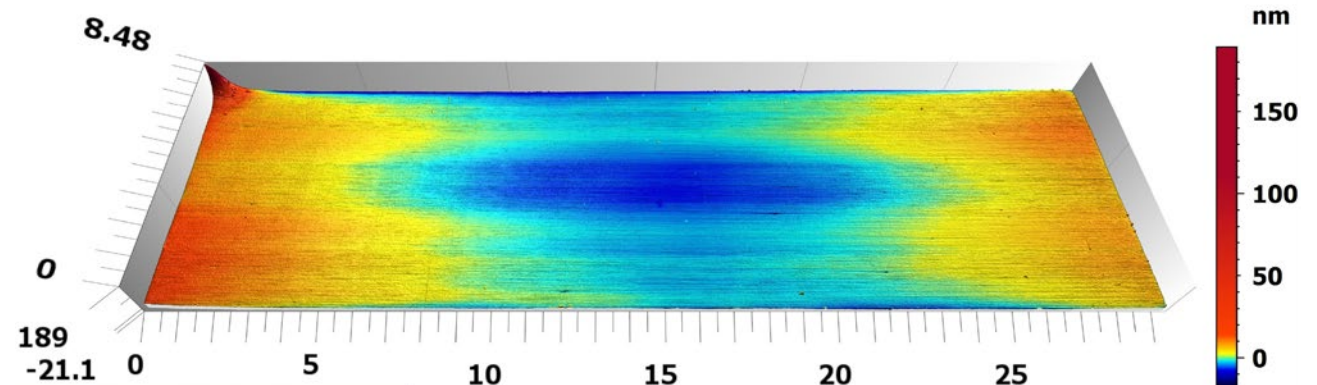
### wear measurement and characterization of cutting edges

Through image correction and contrast enhancement, the smartWLI systems are able to analyse even very weak interference signals on inclined

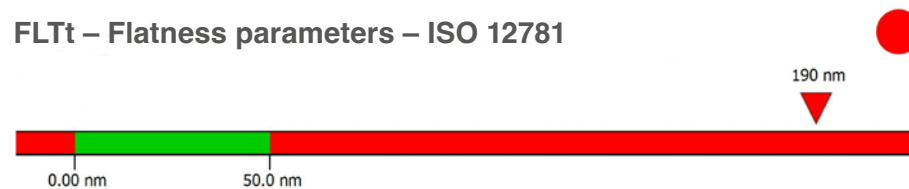
microgeometries and can be used with lenses with moderate magnification to measure cutting edges.



## carbide gauge block



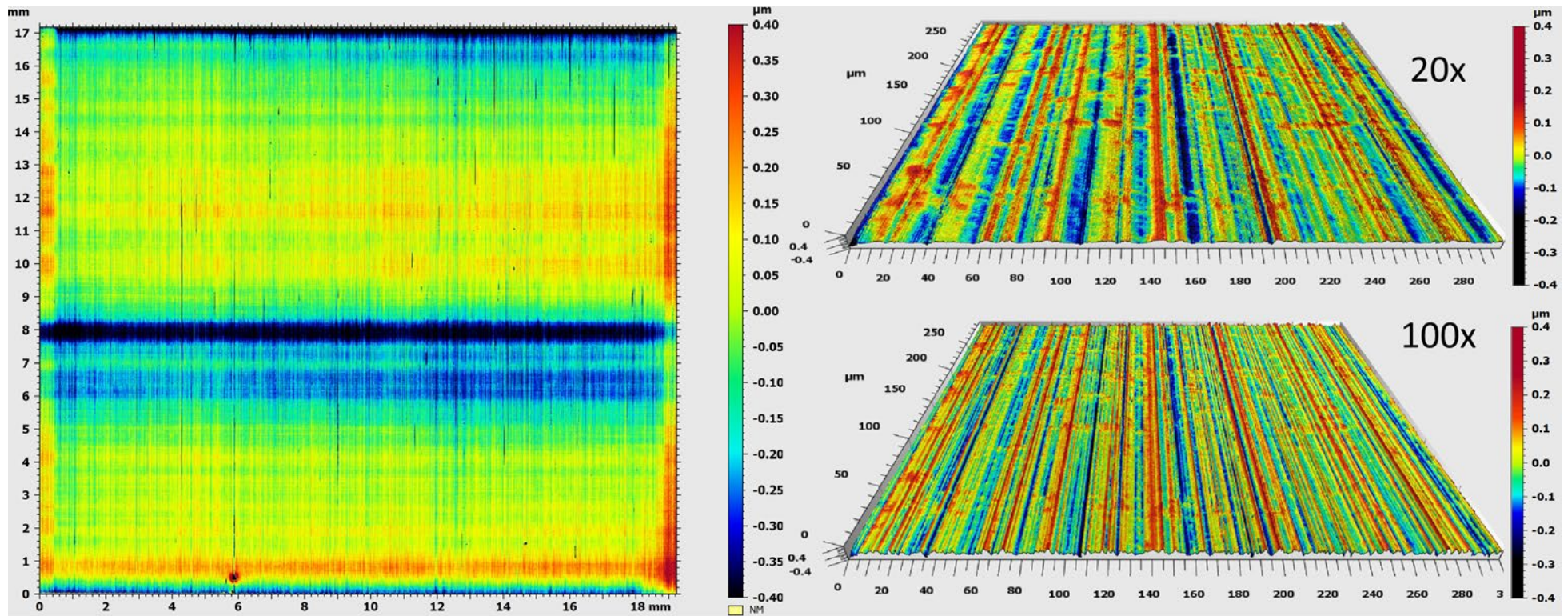
FLTt – Flatness parameters – ISO 12781



## damaged gauge block

Gauge blocks are important for verifying the accuracy of measuring instruments. Optical profilers from the smartWLI series can be used to verify gauge blocks. The material is corrosion-resistant, but a fall from the table onto the floor caused damage to the edge.

## fine grind surface



### behind the limitation of roughness measurements

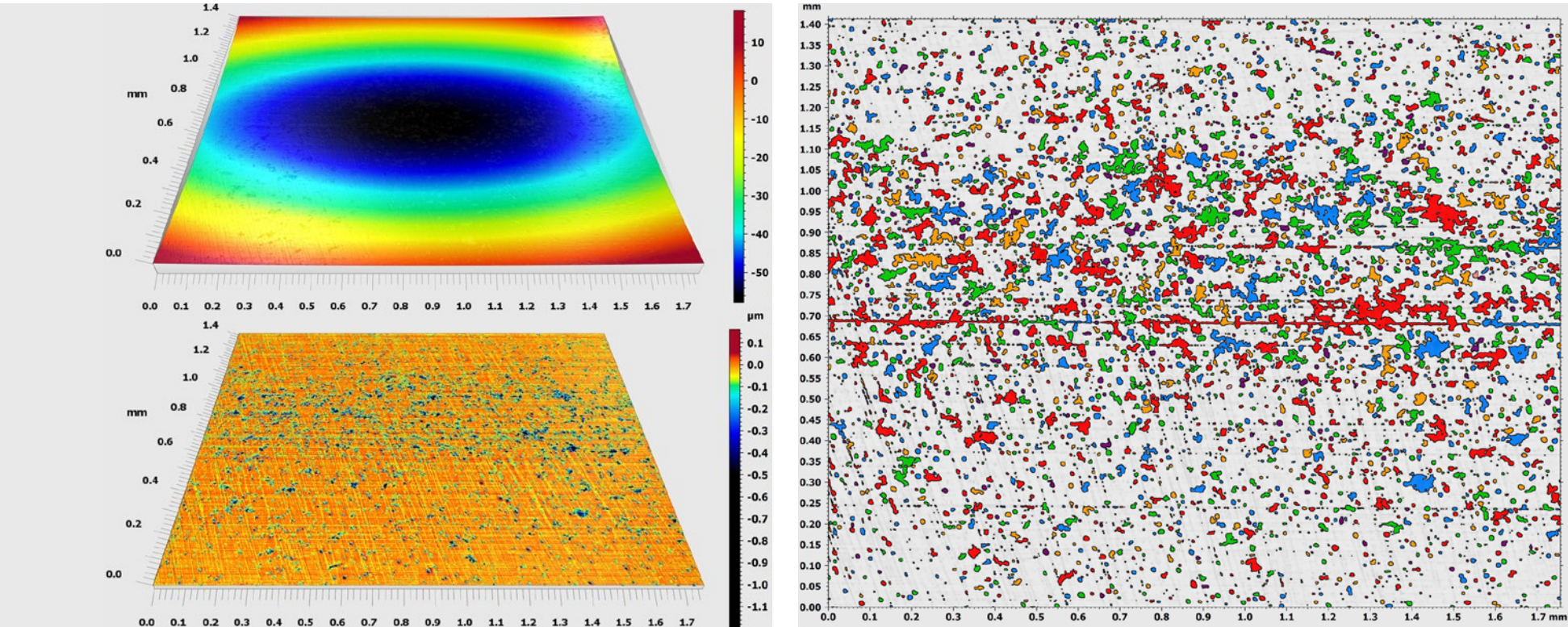
Area B of the stainless-steel master used in the TracOptic project would fall into the Sc2 setting class. The smartWLI next optical profiler used offers the following advantages over a stylus profiler:

- 3D measurements enable a deeper understanding of surface structures compared to 2D profiles
- The larger scan can be used for flatness and shape measurements as

- well as for locating and measuring defects with unknown positions
- the possibility of measuring areas of several cm<sup>2</sup> with the resolution of tactile measuring systems
- high-magnification lenses have approx. 10x higher lateral resolution compared to tactile measuring systems
- smartWLI sensors achieve approx. 100x better height resolution compared to tactile systems



# ball bearing

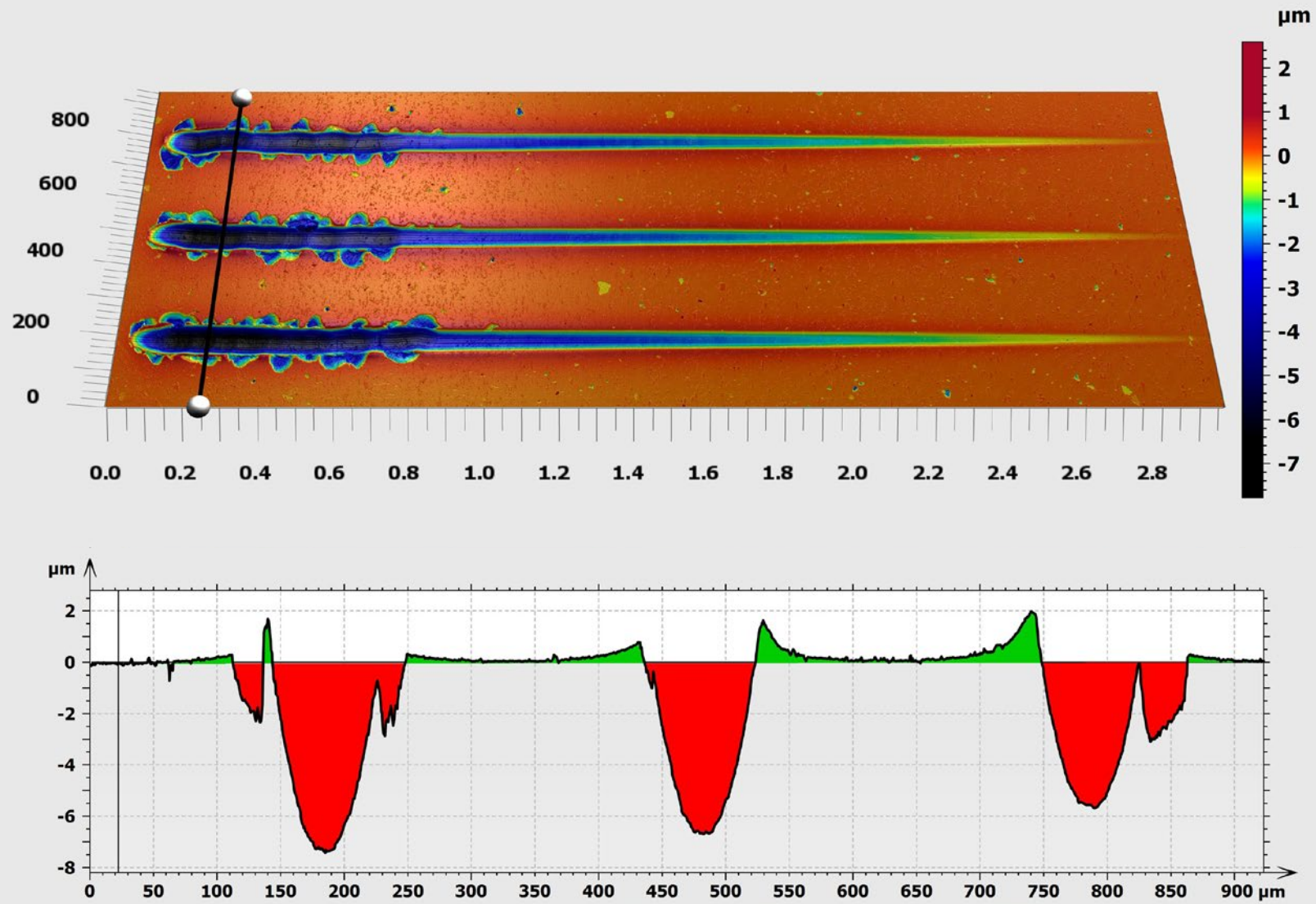


## analysis of the corrosion

The “particle analysis” feature of the MountainsMap® software package enables classification and statistical evaluation of surface structures. Elevation thresholds, watershed models, edge detection or circular models can be used to identify structures. Area, volume, depth/height and aspect ratio can be used for statistical evaluation.

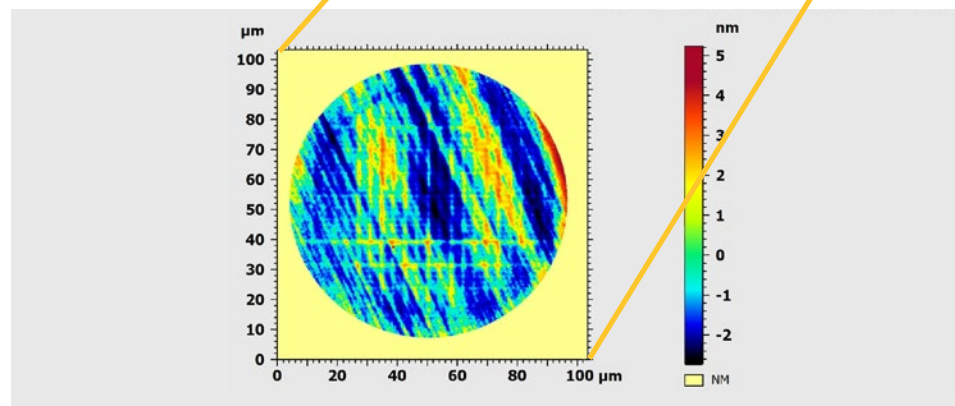
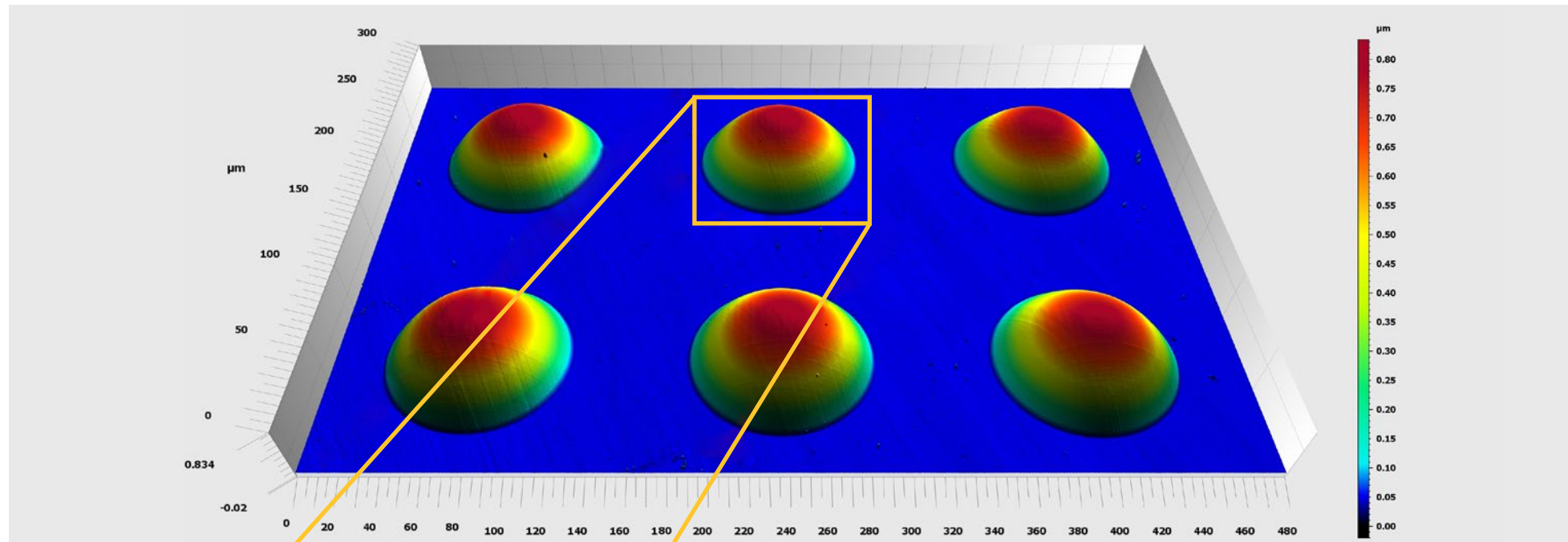
| Information         |                         |
|---------------------|-------------------------|
| Method              | Threshold detection     |
| Particles to detect | Below a threshold value |
| Number of particles | 4530                    |
| Coverage            | 19.5 %                  |
| Density             | 1826 Particles/mm²      |

## tribological tests





# micro lenses



## ISO 25178-2 – Roughness (S-L)

S-filter ( $\lambda_c$ ): Gaussian, 2.5 μm

L-filter ( $\lambda_c$ ): Gaussian, 0.08 mm, Ends not cut

## Height parameters

Sa 0.720 nm



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